



# **Product Segments**

- Comfort Motion
- Ergo Motion

TiMOTION's TA9 series linear actuator was designed as an economical, compact solution specifically for the furniture industry where force cannot be sacrificed. This linear actuator is designed with a custom gear box, molded with a specially formulated plastic material which allows the TA9 to support load ratings up to 2500N. An EMC certification has been attained for this series, which is also available with optional IP54 or IP66 protection.

#### **General Features**

Voltage of motor 12V DC or 24V DC

Maximum load 2,500N in push

Maximum load 1,000N in pull

Maximum speed at full load 24.5mm/s

(with 300N in a push or pull condition)

 $\begin{tabular}{ll} Minimum installation dimension & $\geq$ Stroke + 140mm \\ Color & Black or grey \\ IP rating & Up to IP66 \\ \end{tabular}$ 

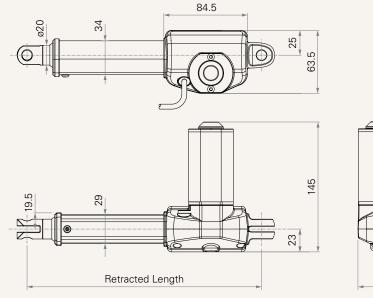
Certificate IEC60601-1, ES60601-1, IEC60601-1-2,

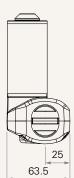
UL962, EMC +5°C~+45°C

Operational temperature range  $+5^{\circ}\text{C} \sim +45^{\circ}\text{C}$ Options Hall sensor(s)

#### **Drawing**

Standard Dimensions (mm)





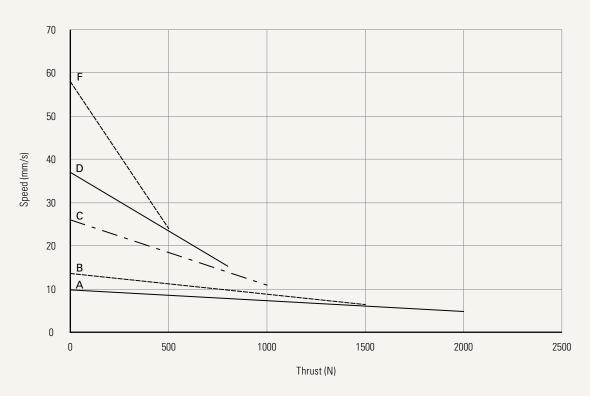
CODE	Load (N)		Self Locking	Typical Current	Typical Speed (mm/s)	
	Push	Pull	Force (N)	with Load (A)	No Load 32V DC	With Load 24V DC
Motor Spee	ed (4100RPM)					
Α	2000	1000	2000	2.8	9.8	4.8
В	1500	1000	800	2.8	13.6	6.4
С	1000	1000	300	3.2	26.0	10.9
D	800	800	200	3.5	37.0	15.3
F	500	500	100	3.5	58.0	24.0
Motor Spee	ed (3800RPM)					
G	2500	1000	2500	2.8	9.5	5.0
Н	2000	1000	1000	3.0	13.3	7.0
ı	1500	1000	500	4.0	26.2	11.0
K	1000	1000	250	4.0	36.5	16.0
L	700	700	150	4.0	57.0	24.0
Motor Spee	ed (3300RPM)					
М	1500	1000	1500	1.8	8.0	4.0
N	1000	1000	800	1.8	11.2	5.9
0	500	500	300	1.4	21.6	11.3
P	400	400	200	1.4	30.0	15.7
Q	300	300	100	1.4	47.0	24.5
Motor Spee	ed (2200RPM)					
V	2000	1000	2000	1.5	5.7	2.6
R	1500	1000	1000	1.5	8.2	3.7
S	1000	1000	500	1.5	15.4	6.0
Т	700	500	250	1.3	22.8	10.0
U	500	300	150	1.3	36.0	16.0

#### Note

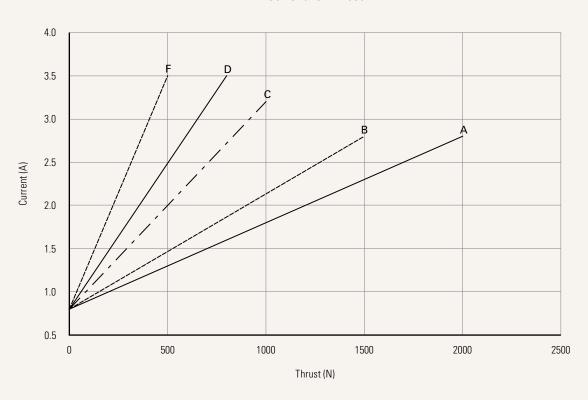
- 1 The current & speed in table are tested when the actuator is extending under push load..
- 2 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC; speed will be similar for both voltages.
- 3 The current & speed in table and diagram are tested with TiMOTION control boxes, and there will be around 10% tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32V DC. At rated load, the voltage output will be around 24V DC)

Motor Speed (4100RPM)

Speed vs. Thrust



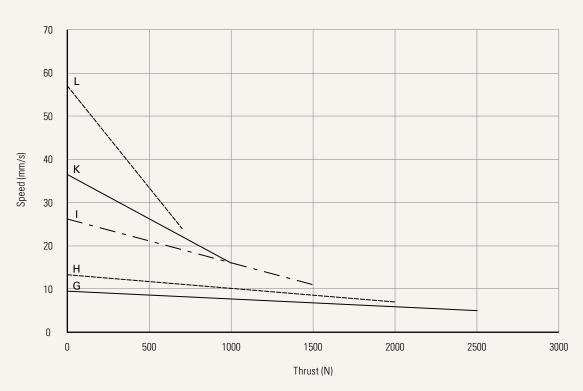
Current vs. Thrust



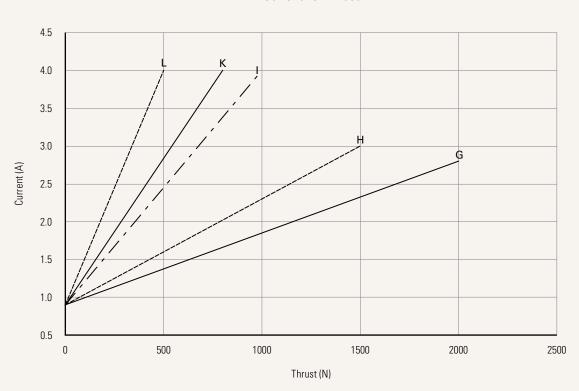


Motor Speed (3800RPM)

Speed vs. Thrust



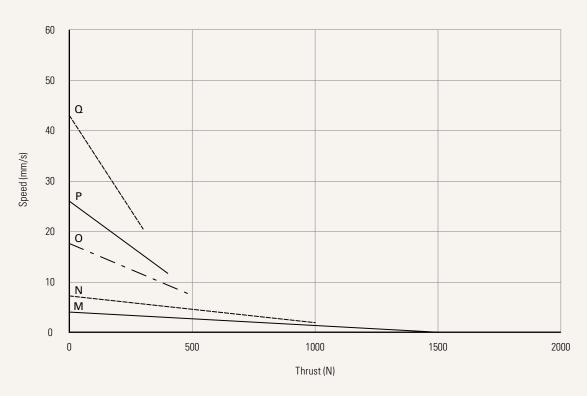
Current vs. Thrust



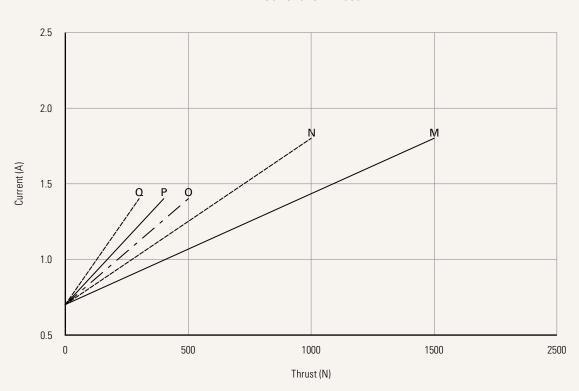


Motor Speed (3300RPM)

Speed vs. Thrust



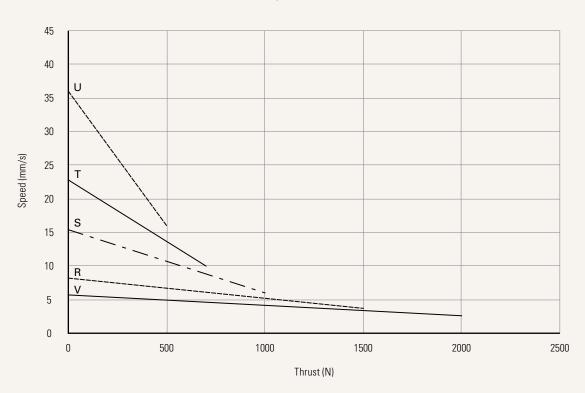
Current vs. Thrust



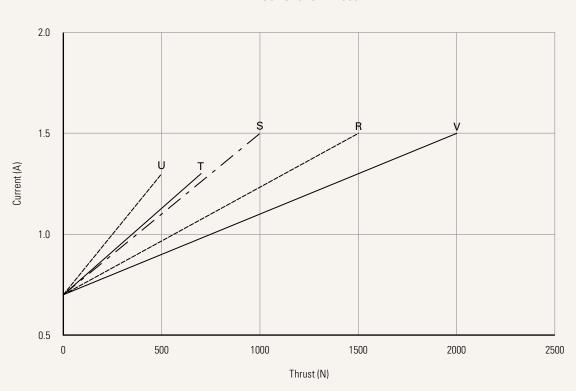


Motor Speed (2200RPM)

Speed vs. Thrust



Current vs. Thrust





# TA9 Ordering Key



Version: 20141208-I

TA9

Voltage	1 = 12V	2 = 24V			
Load and Speed	See page 2				
Stroke (mm)					
Retracted Length mm) See page 8	Stroke + 140 (For front attachment 1, 2)  Stroke + 153 (For front attachment 3, 4)  Note: before selecting retracted length, please refer to the additional retracted length chart				
Rear Attachment mm) See page 8	1 = Hole 8, slot 5				
Front Attachment mm) See page 8	1 = Hole 8	3 = U clevis, slot 6, hole 8			
Direction of Rear Attachment Counterclockwise) See page 9	1 = 0°	2 = 90°			
Color	1 = Black	2 = Grey (Pantone 428C)			
P Rating	1 = Without	2 = IP54	3 = IP66		
Special Functions 0 = Without (standard) 2 = Standard push only for Spindle Sub-Assembly					
Functions for Limit Switches See page 9	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + third one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + third one in between to send signal				
Output Signals	0 = Without	4 = One Hall sensor	5 = Two Hall sensors		
Connector See page 9	1 = DIN 6P, 90° plug	2 = Tinned leads			
Cable Length (mm)	1 = Straight, 500 2 = Straight, 750	3 = Straight, 1000 4 = Straight, 1250	5 = Straight, 1500 6 = Straight, 2000	7 = Coiled, 200 8 = Coiled, 400	

# TA9 Ordering Key Appendix



#### Retracted Length (mm)

TA Series	Safety Stroke Limit	Additional Stroke	Additional Invalid Length
TA9	200	0 < additional stroke ≤ 50	5

#### Note

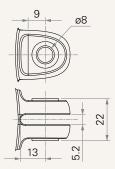
1 Above stroke recommendation is based on safety stroke limit, for each additional 50mm stroke, it needs to add 5mm for the retracted length.

#### For example

- 1 If TA9's stroke is 201mm, the retracted length = 201mm + invalid length + 5mm.
- 2 If TA9's stroke is 300mm, the retracted length = 300mm + invalid length +10mm.

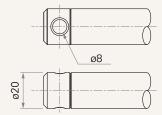
#### Rear Attachment (mm)

1 = Hole 8, slot 5

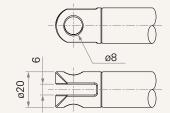


# Front Attachment (mm)

1 = Hole 8



3 = U clevis, slot 6, hole 8

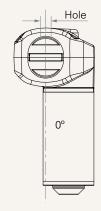


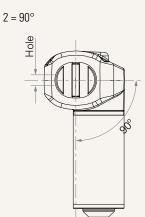
# **TA9** Ordering Key Appendix



#### **Direction of Rear Attachment (Counterclockwise)**





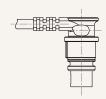


#### **Functions for Limit Switches**

Wire Definitions							
CODE	Pin						
	1 (Green)	2 (Red)	3 (White)	4 (Black)	5 (Yellow)	<b>6</b> (Blue)	
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A	
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A	
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch	
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch	

# Connector

1 = DIN 6P, 90° plug



2 = Tinned leads

